The Brownian Ratchet Revisited: Multiple Filamentous Growth



Introduction

The growth of filamentous protein polymers can do work against molecular or intracellular objects that resist movement. The *Brownian ratchet* (**BR**) model was developed to describe such systems [2]. In this work, we use a continuous diffusion formalism for the polymerization of a **BR** instead of the original random-walk approach. For a more details and results, see [1].

Diffusion Formalism: One Filament

• Represent the position of a filament tip, $\mathbf{X}(t)$, as a continuous diffusion process where δ : the length of a monomer, $D_a = (\alpha + \beta)\delta^2/2, \qquad V_a = (\alpha - \beta)\delta,$ (1) and α , β : polymerization & depolymerization rates. • $f_{\mathbf{X}}(x, t)$: probability density function (*pdf*) for the filament tip (2)

$$\frac{\partial f_{\mathbf{X}}(x,t)}{\partial t} = D_a \frac{\partial^2 f_{\mathbf{X}}(x,t)}{\partial x^2} - V_a \frac{\partial f_{\mathbf{X}}(x,t)}{\partial x}$$

• Single filament without a barrier: $f_{\mathbf{X}}(x,t) = e^{-\frac{(x-V_a t)^2}{4D_a t}} / \sqrt{4\pi D_a t}$.

• $f_{\mathbf{X}}(x, t)$: traveling peak at $x = V_a t$, with increasing dispersion.

Filamentous Bundle: No Barrier

- Let $\mathbf{X}_i(t)$ (i = 1, 2, ..., N) be N independent, identical filaments • Let $\mathbf{X}^{(k)}(t)$ be the position of the k^{th} longest filament, when the filament positions are ordered from longest to shortest: $\mathbf{X}^{(1)}(t) \ge \ldots \ge \mathbf{X}^{(k-1)}(t) \ge \mathbf{X}^{(k)}(t) \ge \mathbf{X}^{(k+1)}(t) \ge \ldots \ge \mathbf{X}^{(N)}(t).$ • The formula for the *pdf* of the k^{th} longest filament:
- $f_{\mathbf{X}^{(k)}}(x,t) = \frac{N!}{(k-1)!(N-k)!} F_{\mathbf{X}}(x,t)^{N-k} \left[1 F_{\mathbf{X}}(x,t)\right]^{N-k} \left[1 F_{\mathbf{X}}(x,t)^{N-k}\right]^{N-k} \left[1 F_{\mathbf{X}}(x$
- where $F_{\mathbf{X}}(x, t)$ is the cumulative distribution function (*cdf*). • $f_{\mathbf{X}^{(k)}}(x, t)$: single traveling peak with increasing dispersion. • The location of the peak and the velocity of the peak movement: $x^{(k)}(t) = V_a t + \omega_k \sqrt{4D_a t}, \qquad v^{(k)}(t) = V_a + 2\omega_k \sqrt{D_a/t},$ (3) where $\omega_k > \omega_{k+1}$ is a constant that satisfies

$$k = 1 + \frac{1 - \operatorname{erf}(\omega_k)}{2} \left[N - 1 - \sqrt{\pi} \omega_k [1 + \operatorname{erf}(\omega_k)] e^{\omega_k^2} \right].$$
(*t*) is greatest early on, when filaments are even.

- v⁽¹⁾
- The distance between $\mathbf{X}^{(k)}(t)$ and $\mathbf{X}^{(k+1)}(t)$ grows with \sqrt{t} : $x^{(k)}(t) - x^{(k+1)}(t) = 2(\omega_k - \omega_{k+1})\sqrt{D_a t}.$

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Bundle Growth: Fluctuating Barrier

$$(x,t)]^{k-1}f_{\mathbf{X}}(x,t),$$

- Let $\mathbf{Y}(t)$ represent a fluctuating barrier with resistant force *F*, frictional coefficient η_b , and diffusion coefficient D_b .
- **BR**: $\mathbf{X}^{(1)}(t)$ and $\mathbf{Y}(t)$ interact subject to $\mathbf{X}^{(1)}(t) \leq \mathbf{Y}(t)$.
- Easier to study $f({x_i}, y, t)$: joint *pdf* for all of the $X_i(t)$ and Y(t): $\frac{\partial f(\{x_i\}, y, t)}{\partial t} = \sum_{i=1}^{N} \left($
- $k=1 \setminus O_k \cup V_k$ • ξ_i : gap distance between $\mathbf{X}_i(t)$ and $\mathbf{Y}(t)$; *z*: center of mass:

$$\xi_i = y - x_i, (i = 1, 2, ..., N);$$

- Decouple: $f(\{\xi_i\}, z, t) = \phi(\{\xi_i\}, t)P_{\mathbf{Z}}(z, t).$
- Gap distances, $\phi(\{\xi_i\}, t)$, approach a stationary distribution:

$$\phi(\{\xi_i\}) = \epsilon^N \exp\left(-\epsilon \sum_{i=1}^N \xi_i\right), \quad \epsilon = \frac{V_a + F/\eta_b}{ND_b + D_a}.$$
 (6)

• Bundle and barrier, together, undergo diffusion with a drift: $\frac{\partial P_{\mathbf{Z}}(z,t)}{\partial t} = D_z \frac{\partial^2 P_{\mathbf{Z}}(z,t)}{\partial z^2}$

$$D_z = \frac{D_b D_a}{N D_b + D_a}, \qquad V_z = \frac{N D_b V_a - D_a \tilde{F} / \eta_b}{N D_b + D_a}.$$
 (8)

Force-dependent Polymerization

• α is proportional to: intrinsic polymerization rate, α_0 , monomer concentration, c_0 , and the probability that the gap is $\geq \delta$:

$$\alpha = \alpha_0 c_0 e^-$$

- Recall that D_a and V_a are defined in $\epsilon(\alpha) = \frac{(\alpha - \beta)\delta + F/\eta_b}{ND_b + (\alpha + \beta)\delta^2/2}$
- Consider the case of slow depolyme $\widetilde{V}_{z} = \widetilde{\alpha} \frac{N - \widetilde{F}/2}{N + \widetilde{\alpha}/2}, \quad \widetilde{D}_{z} = \frac{\widetilde{\alpha}/2}{N + \widetilde{\alpha}/2}$

nondimensionalized: $\tilde{V}_z = V_z \delta / D_b$, $\widetilde{\alpha}_0 = \alpha_0 c_0 \delta^2 / D_h$, and $\widetilde{F} = F \delta / (\eta_h D_h)$

• Implicit force-velocity and force-fluctuation relations (Fig. 1):

$$\widetilde{F} = \frac{2N\widetilde{V}_z}{\widetilde{V}_z + \widetilde{F} - 2N} - \frac{2N^2 - N\widetilde{F}}{2N - \widetilde{V}_z - \widetilde{F}} \ln\left(\frac{2N\widetilde{V}_z/\widetilde{\alpha}_0}{2N - \widetilde{V}_z - \widetilde{F}}\right), \quad (12a)$$
$$\widetilde{F} = \frac{2N\widetilde{D}_z}{\widetilde{D}_z - 1} - \frac{N}{1 - \widetilde{D}_z} \ln\left(\frac{2N\widetilde{D}_z/\widetilde{\alpha}_0}{1 - \widetilde{D}_z}\right). \quad (12b)$$

 $z = \frac{D_b \sum_{j=1}^N x_j + D_a y}{ND_h + D_a}.$ (5)

$$\frac{z,t)}{2} - V_z \frac{\partial P_{\mathbf{Z}}(z,t)}{\partial z},$$
 (7)

(9)

terms of
$$\alpha$$
, β , and δ in (1):
 $\frac{F}{\eta_b}$
(10)

erization, where
$$\frac{\beta}{\alpha} \approx 0$$
:

$$\overline{2}'_{\widetilde{\alpha}} = \widetilde{\alpha}_0 e^{-\left(\frac{\alpha+F}{N+\widetilde{\alpha}/2}\right)}, \quad (11)$$

,
$$D_z = D_z/D_b$$
, $\tilde{\alpha} = \alpha \delta^2/D_b$,
().



Conclusions

- the other filaments lagging behind.
- filaments in the bundle to move together.
- V_z and D_z both increase with $\alpha_0 c_0$.
- $\widetilde{V}_z = \widetilde{\alpha}_0 e^{-\widetilde{V}_z/N}.$

References

- nian ratchet. *Biophys. J.*, 65:316–324, 1993.

Figure 1: Force-Velocity and Force-Fluctuation Relations. **Top:** Curves are plotted for several values of $\tilde{\alpha}_0$ all with N = 1. Note that as $\alpha_0 c_0 \to \infty$, $V_z \to 2 - \tilde{F}$ and $\tilde{D}_z \to 1$ as expected from [3]. **Bottom:** Curves are plotted for bundles of size N, all with $\tilde{\alpha}_0 = 10$.

• Without a barrier, the bundle grows as a single filament with all

• **BR:** The interactions between the $\mathbf{X}_i(t)$ and $\mathbf{Y}(t)$ allow all N

• V_z and D_z both decrease with an increasing resistant force *F*.

• The critical stalling force F^* , such that $V_z = 0$, is scaled with N. • The free-load velocity V_z when F = 0 is scaled with $\alpha_0 c_0$ and N:

• After being normalized by the critical stalling force F/F^* , $V_z(F/F^*)$ increases with N while $D_z(F/F^*)$ decreases with it.

^[1] C.L. Cole and H. Qian. The brownian ratchet revisited: Diffusion formalism, polymer-barrier attractions, and multiple filamentous bundle growth. (*Submitted*), February 2011.

^[2] C.S. Peskin, G.M. Odell, and G.F. Oster. Cellular motions and thermal fluctuations: the brow-

^[3] H. Qian. A stochastic analysis of a brownian ratchet model for actin-based motility and integrate-and-firing neurons. MCB: Mol. & Cell. Biomech., 1:267–278, 2004.